Dvoretzky's theorem and the complexity of entanglement detection

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We present a lower bound for complexity of entanglement detection which (ultimately) relies on the 1961 Dvoretzky's theorem, a fundamental result from Asymptotic Geometric Analysis asserting that high-dimensional convex sets typically look round when we observe only their section with a randomly chosen subspaces of smaller dimension.

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More on the interface between Asymptotic Geometric Analysis and Quantum Information Theory can be found in the forthcoming book

G. Aubrun and S. Szarek, Alice and Bob meet Banach

of which a preliminary version is available via Aubrun's web page.

- Notation
- Background: Gurvits, Horodeckis, Størmer, Skowronek
- The main result
- Strategy behind the proof:

Tangible version of Dvoretzky's theorem (Milman 1971) Face/vertex counting (Figiel–Lindenstrauss–Milman 1977) Bounds on verticial and facial complexity of sets of quantum states

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- Sketch of the proof
- Conclusions

Before we proceed...an announcement



Fall 2017 (Sep. 4 - Dec. 15): Trimester on

ANALYSIS IN QUANTUM INFORMATION THEORY

- at the Institut Henri Poincaré in Paris
- Pre-school, September 4-8, Cargèse, Corsica
- http://www.ihp.fr/en/activities/trimester-thematic/calendar
- Organizers: G. Aubrun, B. Collins, I. Nechita, S. Szarek
- Don't be shy and let one of us know if you are interested!

Entanglement

A quantum state on a finite-dimensional complex Hilbert space \mathcal{H} is a positive operator of trace 1. Denote by $D = D(\mathcal{H})$ the set of states on \mathcal{H} . Note that

$$\mathrm{D}(\mathcal{H}) = \mathsf{conv}\{|\psi\rangle\langle\psi| \; : \; \psi \in \mathcal{H}, |\psi| = 1\}.$$

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When $\mathcal{H} = \mathcal{H}_1 \otimes \mathcal{H}_2$ is a bipartite Hilbert space, the set of separable states is the subset $Sep(\mathcal{H}) \subset D(\mathcal{H})$ defined as

$$\operatorname{Sep} = \operatorname{Sep}(\mathcal{H}) := \operatorname{conv}\{|\psi_1 \otimes \psi_2\rangle \langle \psi_1 \otimes \psi_2| : \psi_i \in \mathcal{H}_i, |\psi_i| = 1\}.$$

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Elements of $D \setminus Sep$ are called entangled states.

The dichotomy between entanglement vs. separability is fundamental in quantum theory.

 $\label{eq:constraint} Entanglement \ is \ indispensable \ for \ most \ protocols \ of \ quantum \ information \ theory/cryptography/computing/teleportation...$

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A naive – but meaningful – way of measuring complexity of entanglement detection would be determining how well Sep can be approximated by a polytope with $\leq N$ faces.

More generally, it is known (Gurvits 2003) that deciding whether a state is entangled or separable is, in general, NP-hard. Later refinements have been due to Ioannou (2007), Gharibian (2010) and others; in particular some upper bounds were supplied by Brandão et al (2011).

A more structured scheme of witnessing entanglement is given by the following (M_d stands for the space of $n \times n$ complex matrices).

Theorem (The Horodecki criterion 1996)

A state $\rho \in \operatorname{Sep}(\mathbb{C}^d \otimes \mathbb{C}^d)$ is entangled if and only if there is a positive map $\Phi : \operatorname{M}_d \to \operatorname{M}_d$ such that the operator $(\operatorname{Id} \otimes \Phi)\rho$ is not positive semi-definite (one says that Φ witnesses the entanglement of ρ). A more structured scheme of witnessing entanglement is given by the following (M_d stands for the space of $n \times n$ complex matrices).

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A map $M_d \to M_d$ is completely positive (CP) if it is a positive linear combination of maps of the form $\Phi_A : X \mapsto AXA^{\dagger}$. CP maps cannot be witnesses since $Id \otimes \Phi_A = \Phi_{I \otimes A}$ is also positive.

In dimension 2 the cone of positive maps has a rather simple structure.

Theorem (Størmer 1963)

Any positive map $\Phi: M_2 \to M_2$ can be written as $\Phi = \Phi_1 + \Phi_2 \circ T$, where Φ_1, Φ_2 are CP maps and T is the transposition on M_2 .

It follows that a state ρ on $\mathbb{C}^2 \otimes \mathbb{C}^2$ is separable if and only if $(\mathrm{Id} \otimes T)(\rho)$ is positive. The transposition is a universal witness.

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This is specific to dimension 2.

Theorem (Skowronek, unpublished)

Let $d \ge 3$. Let \mathcal{F} be a family of positive maps $M_d \to M_d$ such that any entangled state ρ on $\mathbb{C}^d \otimes \mathbb{C}^d$ is witnessed by an element of \mathcal{F} . Then \mathcal{F} is infinite.

In fact, any closed universal family of witnesses must be uncountable.

Denote by • homotheties with respect to $\rho_* := \frac{I_{\mathcal{H}}}{\dim \mathcal{H}}$:

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Suppose that Φ_1, \ldots, Φ_N are positive maps on M_d such that, for any robustly entangled state ρ on $\mathbb{C}^d \otimes \mathbb{C}^d$, there is an index i such that $(\mathrm{Id} \otimes \Phi_i)(\rho)$ is not positive semi-definite. Then $N \ge \exp(cd^3/\log d)$ for some universal constant c > 0.

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This shows that the set of separable states is complex, and not because of some fine features of its boundary. Results about NP-hardness of entanglement detection have usually focused on boundary effects.

Let $K \subset \mathbb{R}^n$ be a convex compact set with 0 in the interior. Define the verticial and facial dimensions of K as

 $\dim_V(K) := \log \inf \{ \# \operatorname{vertices}(P) : K \subset P \subset 4K \}$

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These are dual concepts since dim_{*F*}(*K*) = dim_{*V*}(*K*°), where $K^{\circ} := \{x \in \mathbb{R}^n : \langle x, y \rangle \leq 1, \forall y \in K\}$ is the polar of *K*.

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One has $\dim_F(K) = O(n)$ and $\dim_V(K) = O(n)$ if (say) the origin is the center of mass of K.

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Another parameter is the asphericity of K defined as

$$a(K) := \inf \left\{ R/r \ : \ rB_2^n \subset K \subset RB_2^n \right\}.$$

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This result is a consequence of the tangible version of Dvoretzky's theorem due to Milman, which gives a sharp formula for the dimension of almost Euclidean sections of convex bodies.

If $K \subset \mathbb{R}^n$ is a convex body such that $rB_2^n \subset K$ and M = M(K) denotes the average of the "norm" $\|\cdot\|_K$ over the sphere, then K has **lots of** almost Euclidean sections of dimension $k = \Omega(nr^2M^2)$.

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Thus the facial dimension of K exceeds ck. Applying the same argument to K° and using the inequality $M(K)M(K^{\circ}) \ge 1$ yields the FLM bound.

We illustrate the FLM bound on some examples where it is sharp up to polylog factors

$$\dim_V(K) \cdot \dim_F(K) \ge c \left(\frac{n}{a(K)}\right)^2$$

K	dimension	a(K)	$\dim_V(K)$	$\dim_F(K)$
B_2^n	п	1	$\Theta(n)$	$\Theta(n)$
$[-1,1]^n$	п	\sqrt{n}	$\Theta(n)$	$\Theta(\log n)$
Δ_n	n	n	$\Theta(\log n)$	$\Theta(\log n)$

Recall that B_2^n is the *n*-dimensional Euclidean ball, while Δ_n is the *n*-dimensional simplex.

Quantum-related examples

And here are some more examples related to entanglement detection.

K	dimension	a(K)	$\dim_V(K)$	$\dim_F(K)$
$\mathrm{D}(\mathbb{C}^m)$	$m^{2} - 1$	m-1		
$\operatorname{Sep}(\mathbb{C}^d\otimes\mathbb{C}^d)$	d^4-1	$d^{2} - 1$		

The value of a(D) is elementary to compute; the value of a(Sep) is due to Gurvits-Barnum (2002).

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- There are ε -nets in the sphere of \mathbb{C}^d with $(2/\varepsilon)^{2d} = e^{\Theta(d \log(2/\varepsilon))}$ elements.
- For a well chosen (e.g., random) $\frac{1}{10}$ -net \mathscr{N} in the unit sphere of \mathbb{C}^m and $P = \operatorname{conv}\{|\psi\rangle\langle\psi| : \psi \in \mathscr{N}\}$, we have $\frac{1}{4} \bullet \mathrm{D} \subset P \subset \mathrm{D}$.

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- Similarly, for any $\frac{1}{10d}$ -net \mathcal{N}' in the unit sphere of \mathbb{C}^d and

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However, it is conceivable that we actually have $\dim_F(\text{Sep}) = \Theta(d^4)$.

Let Φ_1, \ldots, Φ_N be N positive maps on M_d with the property that for every robustly entangled state ρ , there exists an index *i* such that $(\Phi_i \otimes Id)(\rho)$ is not positive. This hypothesis is equivalent to the following inclusion

$$\bigcap_{i=1}^{N} \left\{ \rho \in \mathrm{D}(\mathbb{C}^{d} \otimes \mathbb{C}^{d}) : (\mathrm{Id} \otimes \Phi_{i})(\rho) \text{ is } \mathsf{PSD} \right\} \subset 2 \bullet \mathrm{Sep}.$$

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Next, for simplicity, let us assume first that each Φ_i is trace-preserving, i.e., $\Phi_i(\rho_*) = \rho_*$. Consider the convex body

$$\mathcal{K} = \mathrm{D} \cap igcap_{i=1}^{N} (\mathrm{Id} \otimes \Phi_i)^{-1}(\mathrm{D})$$

which satisfies $\operatorname{Sep} \subset K \subset 2 \bullet \operatorname{Sep}$.

Let Φ_1, \ldots, Φ_N be N positive maps on M_d with the property that for every robustly entangled state ρ , there exists an index *i* such that $(\Phi_i \otimes Id)(\rho)$ is not positive. This hypothesis is equivalent to the following inclusion

$$\bigcap_{i=1}^{N} \left\{ \rho \in \mathrm{D}(\mathbb{C}^{d} \otimes \mathbb{C}^{d}) : (\mathrm{Id} \otimes \Phi_{i})(\rho) \text{ is } \mathsf{PSD} \right\} \subset 2 \bullet \mathrm{Sep.}$$

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which satisfies $\text{Sep} \subset K \subset 2 \bullet \text{Sep}$. Note the trace-preserving condition assures that for all *i*'s we are \bullet -dilating with respect to the same point.

Since the facial dimension of $D(\mathbb{C}^d \otimes \mathbb{C}^d)$ is of order d^2 , there exists a polytope P with at most $\exp(Cd^2)$ facets such that $\frac{1}{2} \bullet D \subset P \subset D$. Then the polytope

$$Q = P \cap \bigcap_{i=1}^{N} (\mathrm{Id} \otimes \Phi_i)^{-1}(P)$$

satisfies $\frac{1}{2} \bullet \text{Sep} \subset \frac{1}{2} \bullet K \subset Q \subset K \subset 2 \bullet \text{Sep.}$ Since

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Since the facial dimension of Sep is $\Omega(d^3/\log d)$, it follows that

$$\log((N+1)\exp(Cd^2)) \geqslant cd^3/\log d$$

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The general situation (without the trace-preserving restriction) is handled similarly starting with the assumption that $(1 - \frac{1}{2d}) \bullet D \subset P \subset D$.

Conclusion

We illustrated the complexity of robust entanglement by showing that super-exponentially many positive maps are needed to detect it – at least if used non-adaptively/without reflection.

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The proof is via a facet-counting argument (even if the set of separable states is not a polytope itself) and ultimately relies on the bound due to Figiel–Lindenstrauss–Milman which asserts that – between (i) the number of vertices, (ii) the number of facets, and (iii) asphericity – complexity must lie somewhere.

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Can this approach be used to handle other problems in complexity theory?

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Can this approach be used to handle other problems in complexity theory? Some other directions in which this work can be continued are:

- Upper bounds; in particular, what is the order of $d_F(Sep)$?
- Less/more robust entanglement, i.e., replacing $rac{1}{2}$ with $arepsilon\in(0,1)$
- What if we use witnesses $\Phi : M_d \to M_m$, where m = poly(d)?
- The multipartite or "unbalanced" $(\mathcal{H} = \mathbb{C}^d \otimes \mathbb{C}^m)$ setting